

# University of Wisconsin Madison

2008 SAE Clean Snowmobile Challenge

Electric Sled Design Presentation

Presented by:

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# **Bucky EV – Redefining Electric!**

University of Wisconsin SAE Snowmobile Team





# Design Emphasis

Parameter	NSF Emphasis	CSC Emphasis	UW Emphasis	
Range	Primary	Secondary (100 points)	Primary	
Towing Capacity	Primary	Secondary (100 points)	Primary	
Weight	Secondary	Secondary (100 points)	Secondary	
Handling	Minor (safety only)	Secondary (125 points)	Secondary	
Acceleration	None	Minor (50 points)	Primary	
Noise	None	Primary (300 points)	Secondary (225 pts effectively random)	



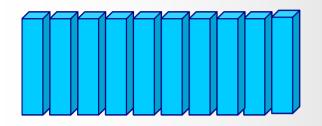
# Specific Design Goals

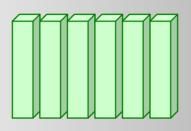
Parameter	Competition Goal	UW Goal	UW Achieved
Range	≥ 16 km (10 mi)	≥ 32 km (20 mi)	30 km (18.6 mi)
Top Speed (IC goal)	≥ 70 km/hr (45 mph)	≥ 140 km/hr (90 mph)	≥ 122 km/hr (76 mph)
Acceleration (150 m)	≤12 s	≤10 s	6.9 s
Emissions	Zero	Zero	Z <mark>ero</mark>
Weight		≤ 340 kg (750 lb)	313 kg (691 <mark>lb)</mark>
Drawbar Pull		≥ 250 kgf (550 lbf)	250 k <mark>gf</mark> (550 lb <mark>f)</mark>
Noise (IC)	≤ 78 dB	≤ 60 dB	56 dB

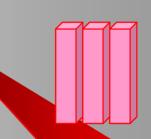


# **Battery Selection**





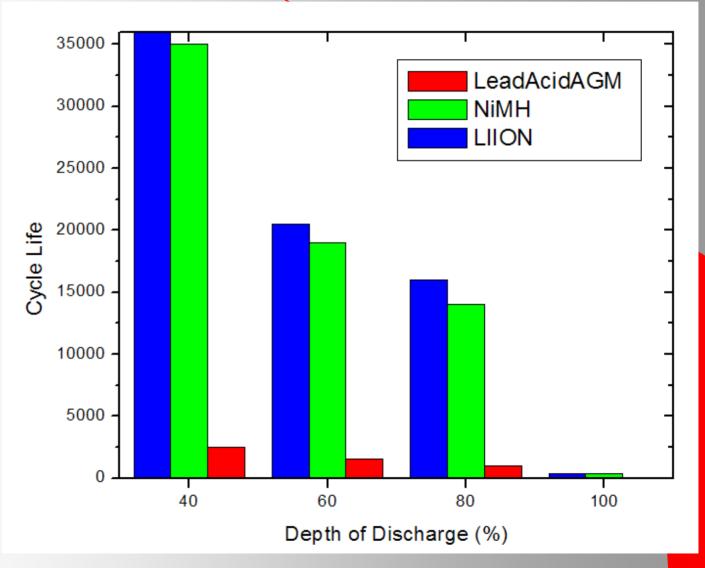




Nickel Metal Hydride	Lead Acid	Lithium-lon
1.25 Volts/Cell	2.12 Volts/Cell	4.00 Volts/Cell
12.5 V → 10 Cells	12.5 V → 6 Cells	12.0 V → 3 Cells



# **Battery Selection**





## **Battery Mounting**





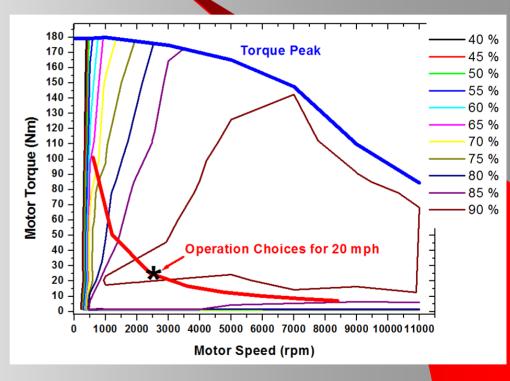
7 strings x 2.8 A-hr = 19.6 A-hr 84 cells x 4 V/cell = 336  $V_{nominal}$ 

84x Milwaukee Tool V28 Li-Ion Battery Modules



# **Delphi EV1 Motor**

# AC Induction

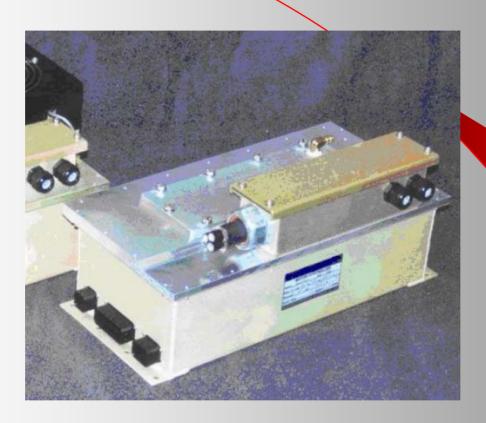


≥ 90% efficient

105 kW continuous



## **Motor Controller**



Azure DMOC445 Motor Controller

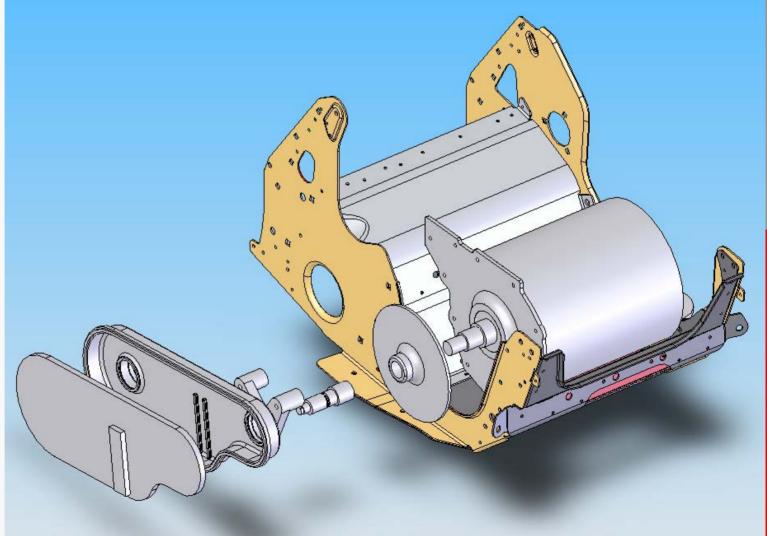


# **Powertrain Implementation**

	Cost (x1)	Strength (x1)	Simplicity (x1.5)	Reliability (x1)	Factor Sum
Belt	7	6	8	4	6.5
Chain	7	9	6	8	7.5
Gear	4	10	4	9	6.5



# **Powertrain Implementation**





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# **Powertrain Integration**





# Vehicle Management

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- Controls
  - Motor torque
  - Coolant circulation pump
  - Cruise control
  - Main battery contactors
  - Indicators/gauges

- Monitors:
  - Battery: V I<sub>string</sub>, T<sub>string</sub>, HV isolation
  - Motor/Inverter: τ<sub>actual</sub>, T<sub>mot/inv</sub>, faults
  - Vehicle Speed
  - Rider torque and brake cmd

# MotoTron Powertrain Control Module

-40° to 130 ° C 18 g Shock Load Immersion to 3 m underwater Matlab Simulink Control Models MotoHawk Automatic Code Gen

# Clean Bucky EV – Redefining Electric!

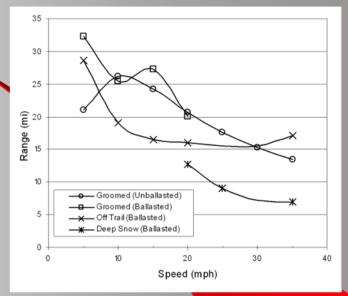
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# Range Predictions

- Pack Capacity
  - 19.6 A-hr = 6.6 kW-hr
- Road load
  - Initial model [Auth] 4.6 kW at 20 mph
  - Testing (reduced pack and ballast)
    - 6 kW at 20 mph (packed trail)
    - 7 kW at 20 mph (another packed trail)
    - 8 kW at 20 mph (deep snow)
    - 10 kW at 20 mph (6-8" soft packed snow)
    - Extremely variable based on snow conditions (and speed)
- Predicted range
  - ≤1 hr at 20 mph
  - 20 mi absolute maximum (optimal conditions, full discharge)
  - 15 mi practical range (typical conditions, limited discharge)





# Range Testing

- Pre-competition testing
  - Snow conditions: 8" snow with 3" track depth
  - 13.7 mi at 20 mph
  - Estimated battery depth-of-discharge: 70-90% (hadn't yet been calibrated)
- Competition testing
  - Snow conditions: Snow-covered road (optimal)
  - Range according to snowmobile odometer: 18.4 mi
  - Very close to goal of 20 mi
- What we learned from competition range test
  - Road load
    - 6 kW typical
    - 24 N-m flat, 35 N-m on incline, 20 N-m descending
  - Target pack depletion: 97%
  - Actual charge removed: 96% (18.8 A-hr / 19.6 A-hr)
  - SoC estimation algorithm very successful!



# **Bucky EV – Redefining Electric!**





# **Sound Testing**

	Left @ 50 ft	Right @ 50 ft	Rider's Head
15 mph	55 dB	57 dB	76 dB
30 mph	58 dB	59 dB	82 dB

Based on mean peak sound level (dBA fast response) of 4-6 constant speed passes, background level ≤40 dB Snow conditions: 2" soft powder on crust above 4" of packed powder



### Acceleration



Beats competition IC minimum of 12 s to 500 ft

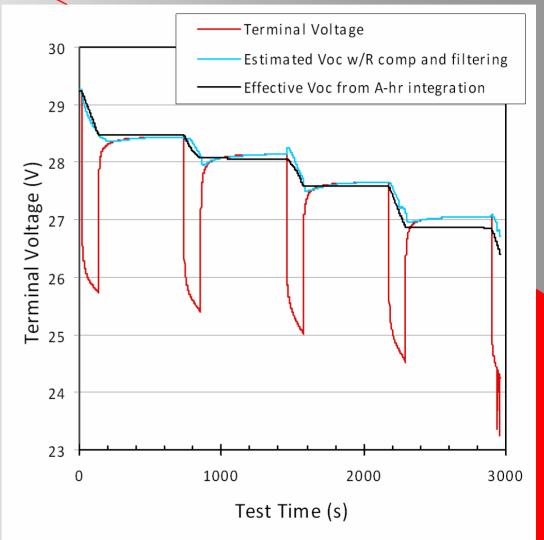


# **Battery Management**

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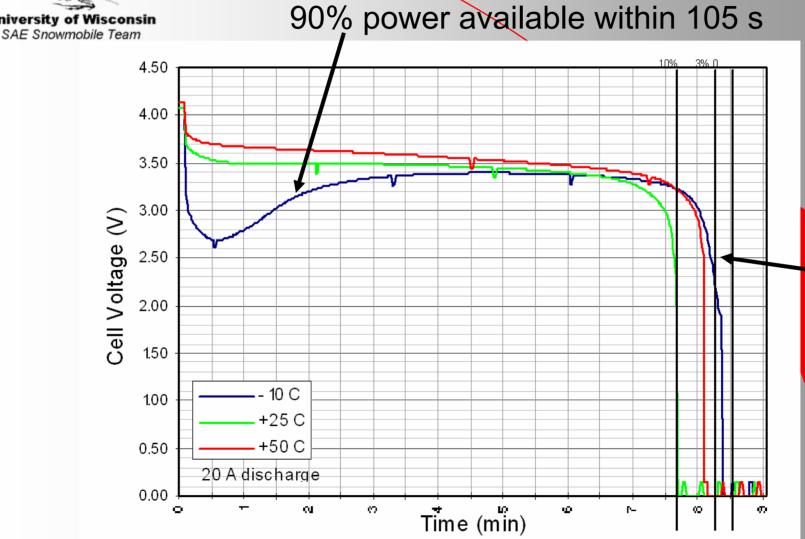
### Estimate state-of-charge (SOC)

- Battery terminal voltage model
  - Voltage source
  - Series resistance
    - •R based on temperature
  - Series RC element
    - •τ,R based on temperature
- Estimate SOC based on
  - •V<sub>terminal</sub>
  - I<sub>instantaneous</sub>, I<sub>LPF</sub>
  - Battery temperature
- Outputs
  - SOC, DTE indications
  - •Warn rider at 10%
  - Terminate operation at 3%





### **Cold Performance**





# **Goal Recap**

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# Questions?





## **Drive Shaft**

